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ABSTRACT

Through interactions with the surrounding water, the behavior of a submerged structure can be considerably affected by neighboring systems. In this thesis, a theoretical and laboratory study of such multi-body and fluid interactions, subject to a set of boundary conditions, constraints and excitations is presented.

In the theoretical section, the effects of simplifying assumptions on the results are discussed. The "scales of motion" along with various parameters found in the ocean environment are investigated. The behavior of ocean based systems subject to earthquake excitations is discussed.

A multi-variable feedback control system is developed to model the behavior of multibody fluid interactions. A direct application would be the control of ocean based structures, using active interaction concepts in the design.

In the study of multi-body and fluid interactions, the common solution techniques (Green's function method and finite-element alternatives) can be inefficient. A "successive Superposition Technique" is presented using "Efficiency Functions". With appropriate discretization or depth averaging, this method can be very useful.

In order to augment present theoretical knowledge, physical modeling criteria are developed. A laboratory study of the behavior of structures in water is carried out using a series of $\frac{1}{200}$ scale, geometrically similar and elastically distorted physical models. The instrumentation used in the experiments is discussed and evaluated.

Time scaled excitations are generated and applied to the models, using an earthquake simulator. The geometric configurations and inertia related properties are varied and various response parameters are measured. Three-dimensional motions of the subsystems, and surface effects along with the pressure distribution on the structures are recorded. The variations of the pressure distributions resulting from interactions are obtained.

A dynamic system identification method is developed to measure the "added mass" properties of the multi-structure system without constraining any of the degrees of freedom. The applications of various signal processing techniques such as Complex Demodulation to the experimental study of Fluid-structure systems are explained.

The importance of transient analysis is emphasized. The coupling of transverse and in-line degrees of freedom are measured. It is shown that the systems with well-spaced modes can behave similar to closely-spaced-mode systems, when placed in a fluid.

William C. Webster 5/23/83

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